

UNIVERSITY OF TWENTE.

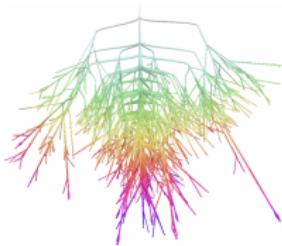
Formal Methods & Tools.

Multi-Core Model Checking

Alfons Laarman

November 14, 2013

State Space Explosion

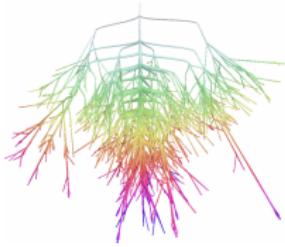


(LaQuSo project)

An exponential problem

- ▶ system data
- ▶ system components
- ▶ property size

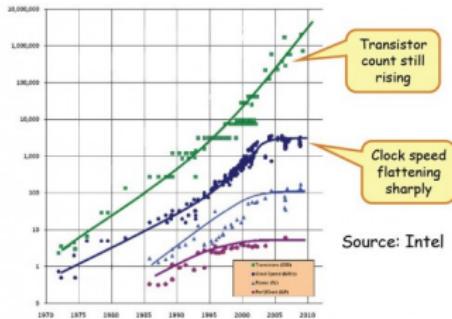
State Space Explosion



(LaQuSo project)

An exponential problem

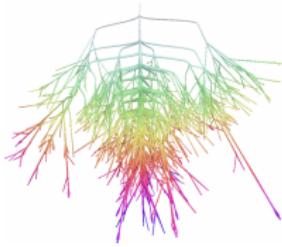
- ▶ system data
- ▶ system components
- ▶ property size



Approach

- ▶ multi-core model checking

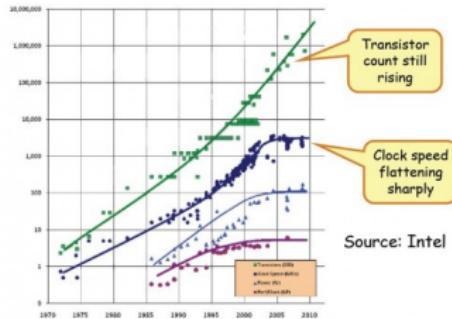
State Space Explosion



(LaQuSo project)

An exponential problem

- ▶ system data
- ▶ system components
- ▶ property size



Approach

- ▶ multi-core model checking
- ▶ Confluence / partial-order reduction
- ▶ Symbolic techniques (BDD-based and SAT-based)
- ▶ On-the-fly techniques
- ▶ Compression techniques

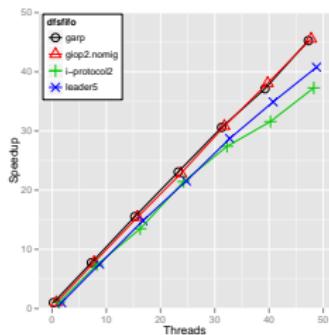
Multi-Core Model Checking

Research questions

- ▶ Can model checking scale (linearly, ideally) on modern multi-cores?

Speedup:
 $S_P = T_{seq}/T_P$

Ideal: $S_P = P$
Linear:
 $S_P = P/c$

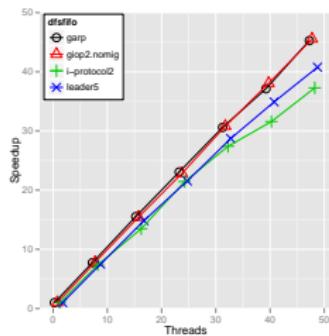


Multi-Core Model Checking

Research questions

- ▶ Can model checking scale (linearly, ideally) on modern multi-cores?
 - ▶ Formalisms: plain, timed, stochastic, etc
 - ▶ Properties: Reachability, LTL, CTL, etc

Speedup:
 $S_P = T_{seq}/T_P$



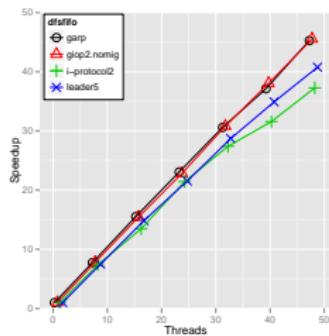
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Multi-Core Model Checking

Research questions

- ▶ Can model checking scale (linearly, ideally) on modern multi-cores?
 - ▶ Formalisms: plain, timed, stochastic, etc
 - ▶ Properties: Reachability, LTL, CTL, etc
- ▶ Are our parallel solutions compatible with other techniques?

Speedup:
 $S_P = T_{seq}/T_P$



Ideal: $S_P = P$
Linear:
 $S_P = P/c$

- +
- ▶ Partial-order reduction (POR)
 - ▶ Symbolic exploration
 - ▶ On-the-fly techniques
 - ▶ Compression techniques

Challenges

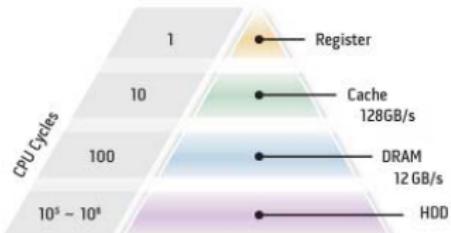
Difficulties of parallelism

- ▶ Correctness of data structures and algorithms

Challenges

Difficulties of parallelism

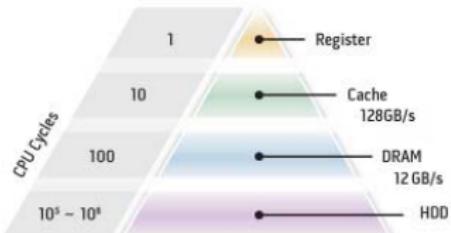
- ▶ Correctness of data structures and algorithms
- ▶ Steep memory hierarchies



Challenges

Difficulties of parallelism

- ▶ Correctness of data structures and algorithms
- ▶ Steep memory hierarchies
- ▶ Cache coherence protocol



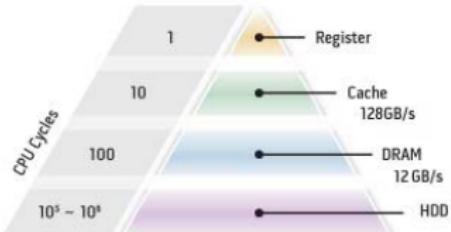
```
#define B (1024*1024*1024)

int main (void) {
    int result = 0;
    for (int i = 0; i < B; i++)
        result++;
    return result;
}
```

Challenges

Difficulties of parallelism

- ▶ Correctness of data structures and algorithms
- ▶ Steep memory hierarchies
- ▶ Cache coherence protocol



```
#define B (1024*1024*1024)
```

```
int main (void) {
    int result = 0;
    for (int i = 0; i < B; i++)
        result++;
    return result;
}
```

```
#define P 16

static void count (void *arg) {
    int *counter = (int *) arg;
    for (int i = 0; i < B / P; i++) (*counter)++;
}

int main (void) {
    pthread_t thread[P];
    int counters[P] = {0};

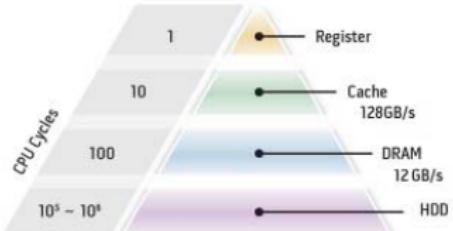
    for (int i = 0; i < P; i++)
        pthread_create (&thread[i], NULL, count, &counters[i]);

    int result = 0;
    for (int i = 0; i < P; i++) {
        pthread_join (thread[i], NULL);
        result += counters[i];
    }
    return result;
}
```

Challenges

Difficulties of parallelism

- ▶ Correctness of data structures and algorithms
- ▶ Steep memory hierarchies
- ▶ Cache coherence protocol



```
#define B (1024*1024*1024)    T = 27
```

```
int main (void) {
    int result = 0;
    for (int i = 0; i < B; i++)
        result++;
    return result;
}
```

```
#define P 16
static void count (void *arg) {
    int *counter = (int *) arg;
    for (int i = 0; i < B / P; i++) (*counter)++;
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int main (void) {
    pthread_t thread[P];
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    for (int i = 0; i < P; i++)
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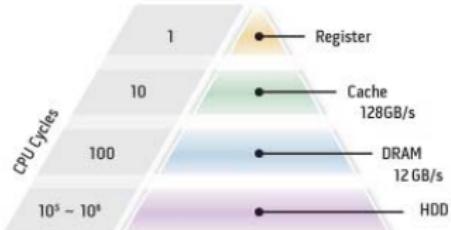
    int result = 0;
    for (int i = 0; i < P; i++) {
        pthread_join (thread[i], NULL);
        result += counters[i];
    }
    return result;
}
```

$T_{16} = 32$

Challenges

Difficulties of parallelism

- ▶ Correctness of data structures and algorithms
- ▶ Steep memory hierarchies
- ▶ Cache coherence protocol (false sharing)



```
#define B (1024*1024*1024)    T = 27
```

```
int main (void) {
    int result = 0;
    for (int i = 0; i < B; i++)
        result++;
    return result;
}
```

```
#define P 16

static void count (void *arg) {
    int *counter = (int *) arg;
    for (int i = 0; i < B / P; i++) (*counter)++;
}

int main (void) {
    pthread_t thread[P];
    int __attribute__((aligned(64))) counters[P] = 0;

    for (int i = 0; i < P; i++)
        pthread_create (&thread[i], NULL, count, &counters[i]);

    int result = 0;
    for (int i = 0; i < P; i++) {
        pthread_join (thread[i], NULL);
        result += counters[i];
    }
    return result;
}
```

$T_{16} = 32$
 $T_{16} = 1.8$

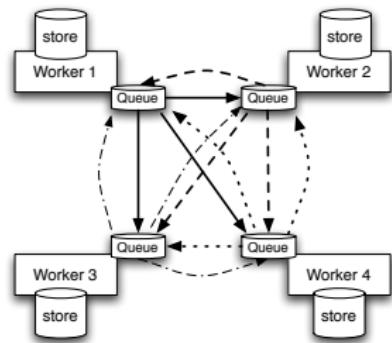
(Explicit-state) reachability

Problem:

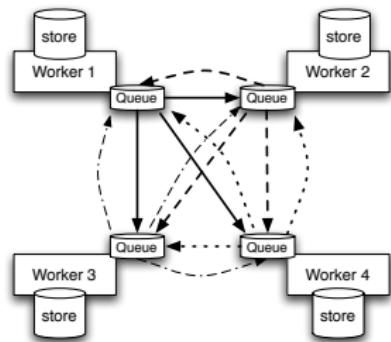
find all reachable states from $s_0 \in S$ using a next-state function: $\text{post}(S) \rightarrow 2^S$

A state $s \in S$ is a (fixed) K -sized vector: $\langle v_1, \dots, v_K \rangle$

Static partitioning or shared hash table



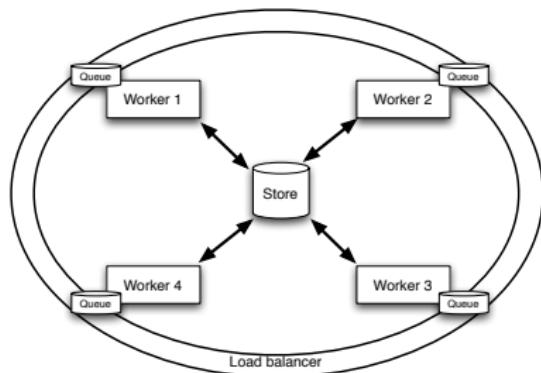
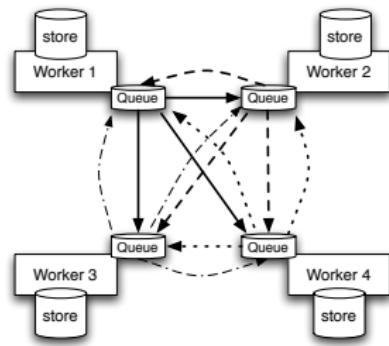
Static partitioning or shared hash table



Static partitioning

- ✗ On-the-fly (BFS)
- ± Scalability (communication on queues)

Static partitioning or shared hash table



Static partitioning

- ✗ On-the-fly (BFS)
- ± Scalability (communication on queues)

Shared hash table

- ✓ On-the-fly: (pseudo) DFS & BFS
- ? Scalability

Lockless Hash Table: Design

LAARMAN, VAN DE POL, WEBER [FMCAD10]

Main bottlenecks

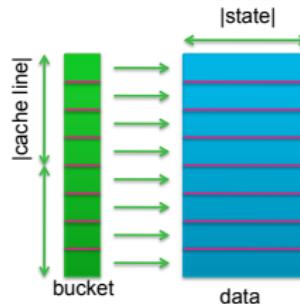
- ▶ State store: concurrent access
- ▶ Graph traversal: Random memory access (bandwidth)

Lockless Hash Table: Design

LAARMAN, VAN DE POL, WEBER [FMCAD10]

Main bottlenecks

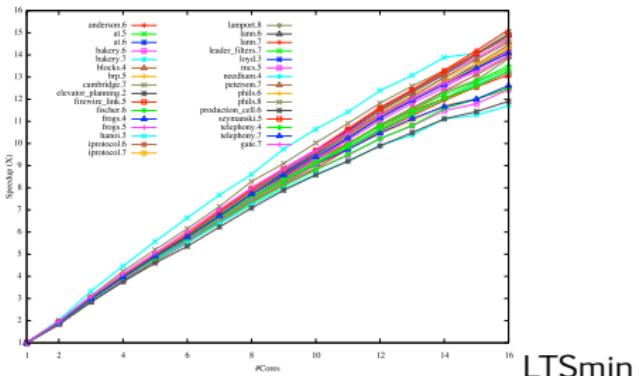
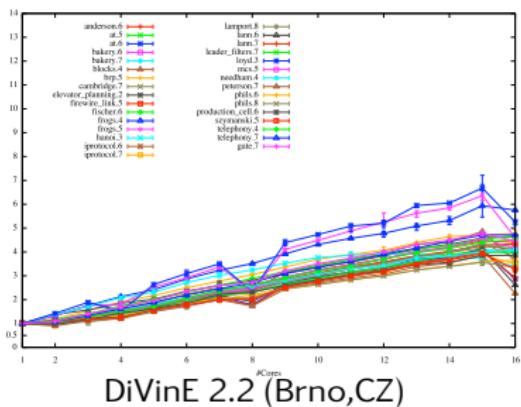
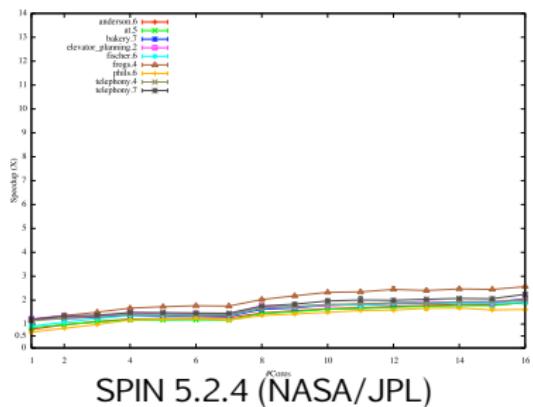
- ▶ State store: concurrent access
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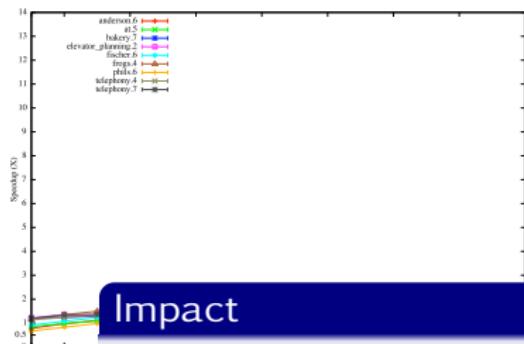
Design

- ▶ Hash memoization
- ▶ Walking the Line
- ▶ In-situ locking

Experiments from 2010 (BEEM database)



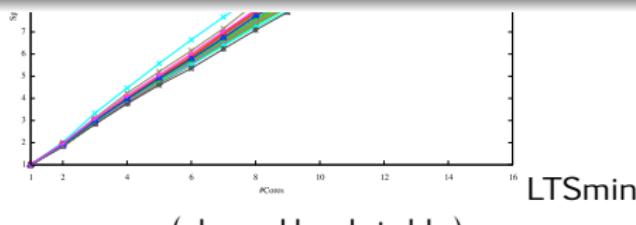
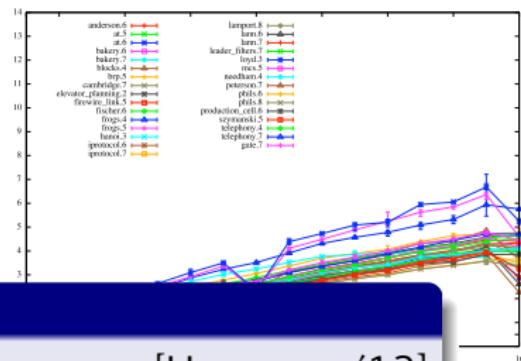
Experiments from 2010 (BEEM database)



Impact

- ▶ SPIN model checker [HOLZMANN'12]
- ▶ GPU model checking [SULEWSKI ET AL '11,12]
- ▶ Parallel BDDs VAN DIJK, LAARMAN, VAN DE POL

[AVOCS12][PDMC12]



Reachability

- ▶ Scalability comes from limiting bandwidth usage
- ▶ Correctness established with model checker

Reachability	✓	?	?	✓	

Explicit state
+ Compression
+ POR
+ On-the-fly

Reachability

- ▶ Scalability comes from limiting bandwidth usage
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Reachability	✓	?	✓	✓	

Explicit state
+ Compression
+ POR
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- ▶ Partial-order reduction can be computed (state) locally

Reachability

- ▶ Scalability comes from limiting bandwidth usage
- ▶ Correctness established with model checker

	Explicit state	+	Compression	+	POR	+	On-the-fly
Reachability	✓	✗	✓	✓			

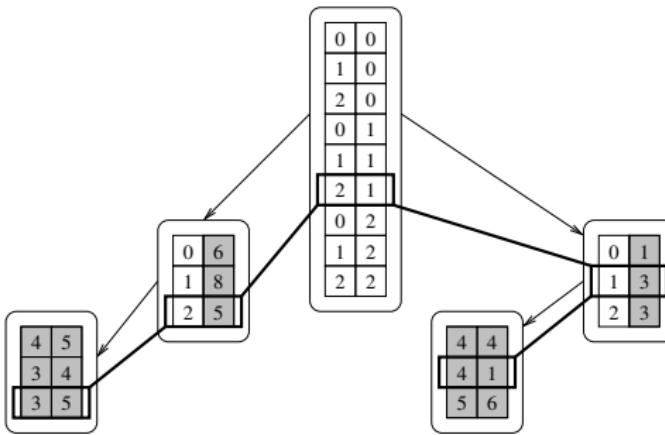
- ▶ Partial-order reduction can be computed (state) locally
- ▶ No compression, but states are often very similar due to **locality**

$$\langle 3, 5, 5, 4, 1, 3 \rangle \rightarrow \langle 3, 5, 9, 3, 1, 3 \rangle$$

Recursive indexing

[HOLZMANN 97][BLOM ET AL. 08]

4	5	6	4	4	1
3	4	8	4	4	1
3	5	5	4	4	1
4	5	6	4	1	3
3	4	8	4	1	3
3	5	5	4	1	3
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3	4	8	5	6	3
3	5	5	5	6	3

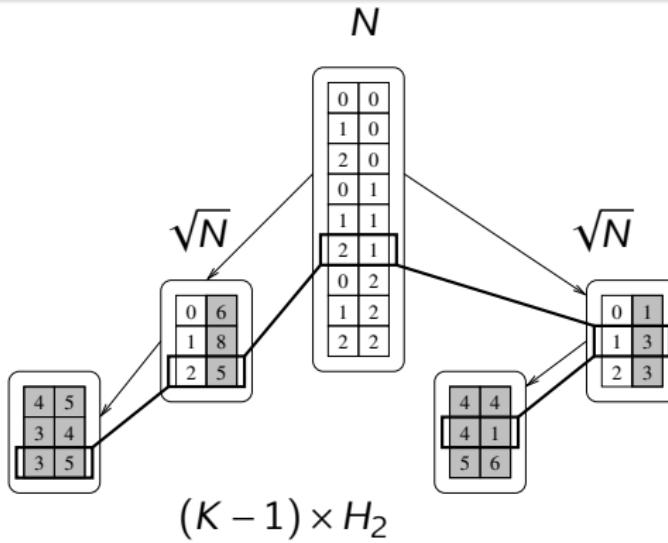
 H_K  $(K - 1) \times H_2$

Recursive indexing

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H_K



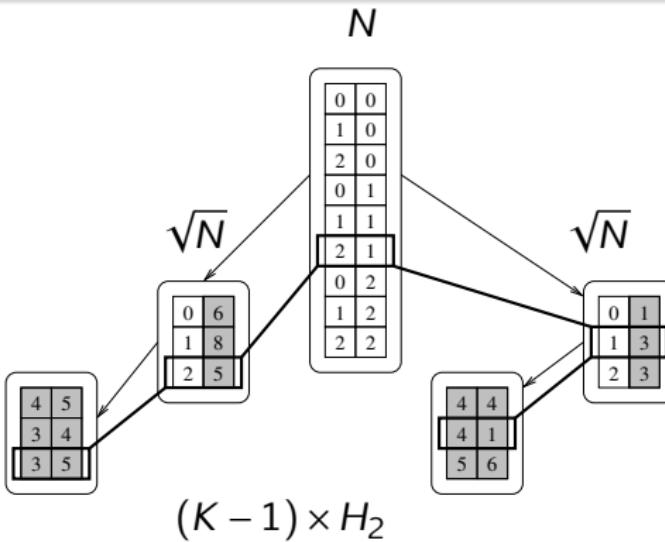
- ✓ Combinatorial \implies balanced tree $(N + 2\sqrt{N} + 4\sqrt[4]{N}) \dots \approx N$
Compresses states of length K to almost 2!

Recursive indexing

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H_K



$(K - 1) \times H_2$

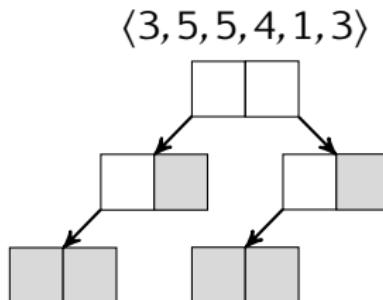
- ✓ Combinatorial \implies balanced tree $(N + 2\sqrt{N} + 4\sqrt[4]{N} \dots \approx N)$
Compresses states of length K to almost 2!
- ✗ Hard to parallelize (flatliners)

Parallel Tree Compression

LAARMAN, VAN DE POL, WEBER [SPIN11]

Solution

- ▶ Temporary binary tree structure on stack

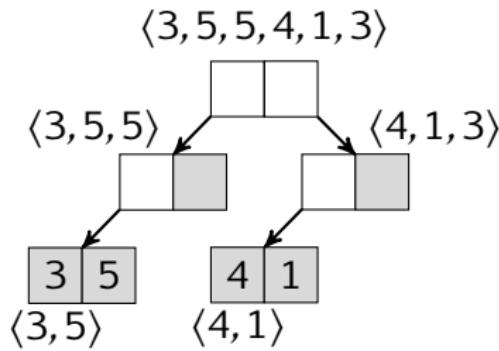


Parallel Tree Compression

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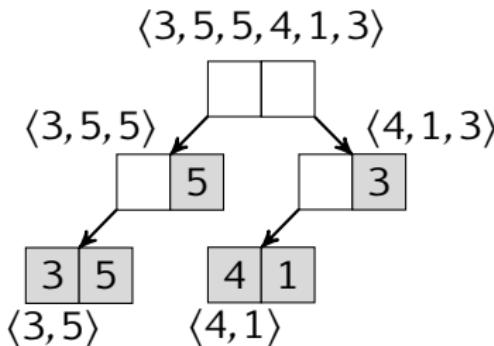
Parallel Tree Compression

LAARMAN, VAN DE POL, WEBER [SPIN11]

Solution

- ▶ Temporary binary tree structure on stack
- ▶ Reuse lockless hash table (merge tables)

4	1
3	5

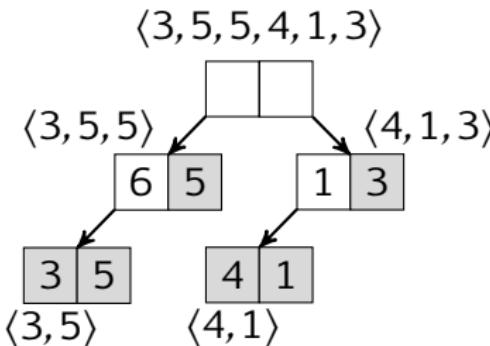
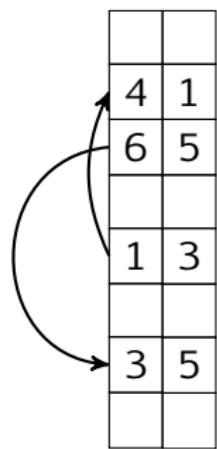


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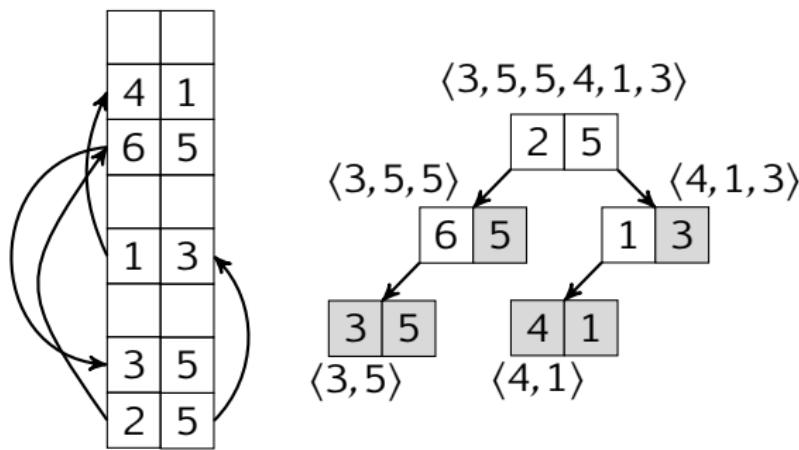


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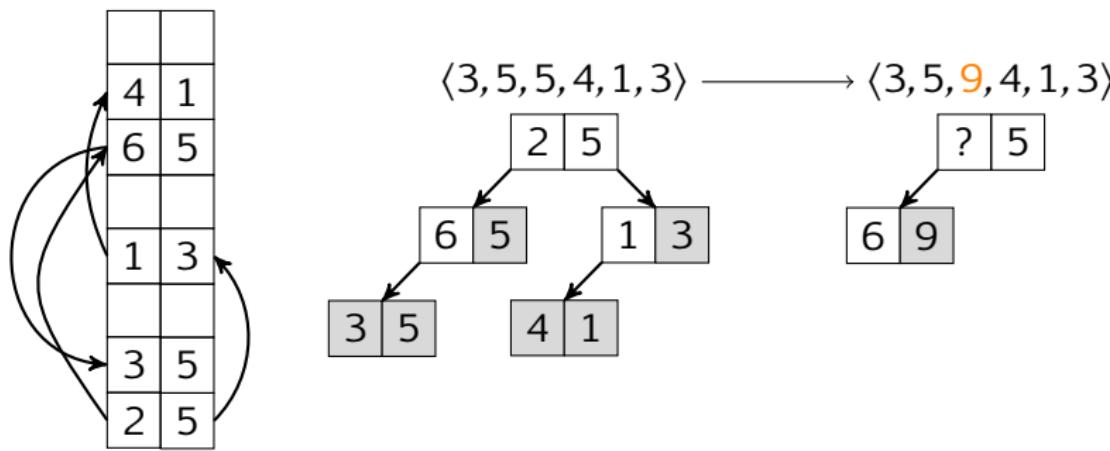


Parallel Tree Compression

LAARMAN, VAN DE POL, WEBER [SPIN11]

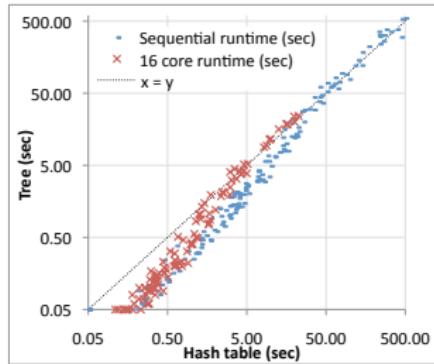
Solution

- ▶ Temporary binary tree structure on stack
- ▶ Reuse lockless hash table (merge tables)
- ▶ Incremental updates: $(K - 1) \rightarrow \log_2(K - 1)$ lookups



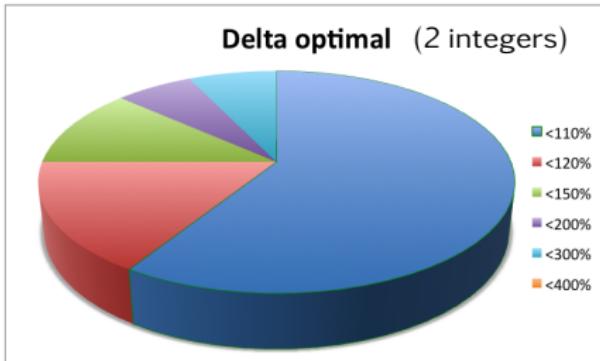
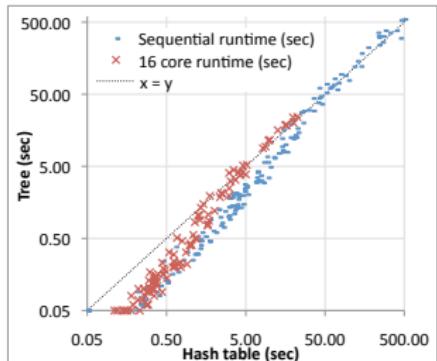
Experiments from 2011 [BEEM database]

LAARMAN, VAN DE POL, WEBER [SPIN11]



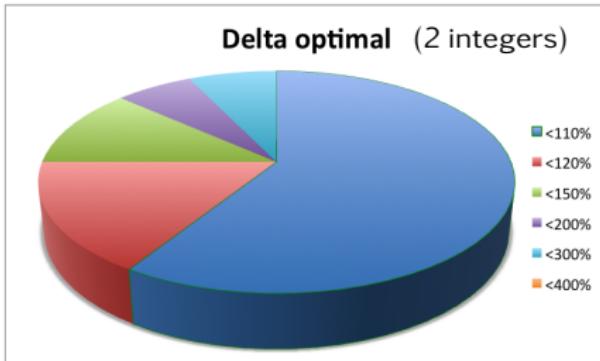
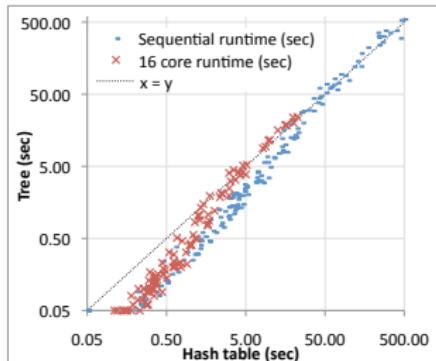
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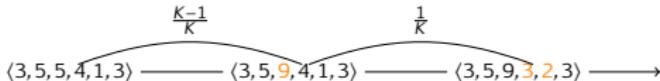
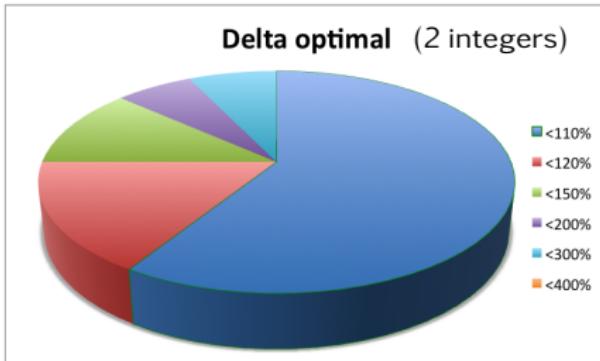
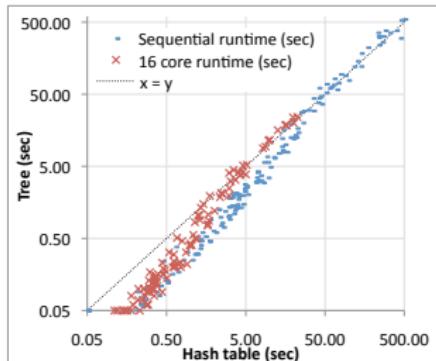
$$\langle 3, 5, 5, 4, 1, 3 \rangle \longrightarrow \langle 3, 5, 9, 4, 1, 3 \rangle \longrightarrow \langle 3, 5, 9, 3, 2, 3 \rangle \longrightarrow$$

Information theoretical *lower bound*?

- View states as stream of variables: $\langle v_1^1, \dots, v_K^1 \rangle, \langle v_1^2, \dots, v_K^2 \rangle, \dots$ with $|v_j^i| = 2^{32}$

Experiments from 2011 [BEEM database]

LAARMAN, VAN DE POL, WEBER [SPIN11]

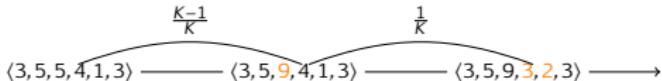
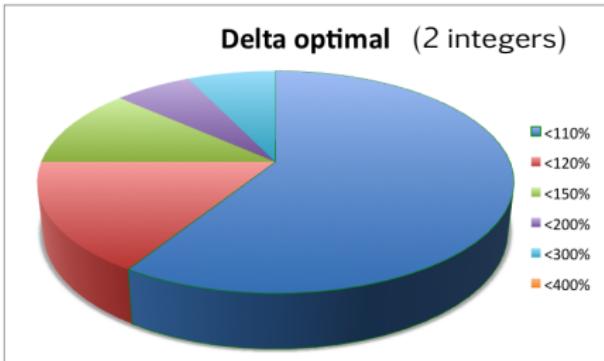
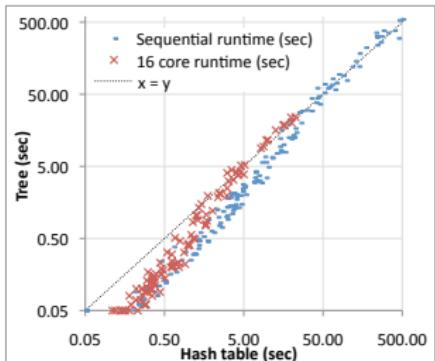


Information theoretical lower bound?

- ▶ View states as stream of variables: $\langle v_1^1, \dots, v_K^1 \rangle, \langle v_1^2, \dots, v_K^2 \rangle, \dots$ with $|v_j^i| = 2^{32}$
- ▶ $p(v_j^i = v_j^{i-1}) = \frac{K-1}{K}$ and $p(v_j^i \neq v_j^{i-1}) = \frac{1}{K}$ (under-estimation)

Experiments from 2011 [BEEM database]

LAARMAN, VAN DE POL, WEBER [SPIN11]

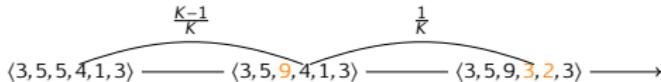
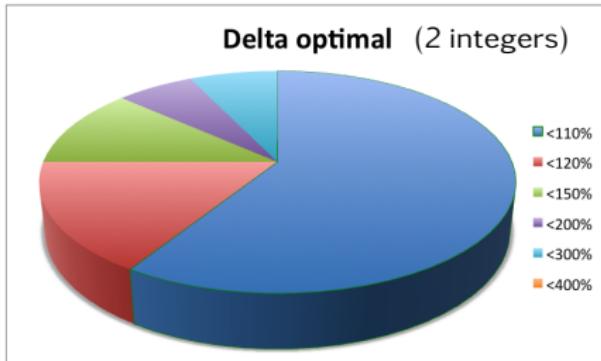
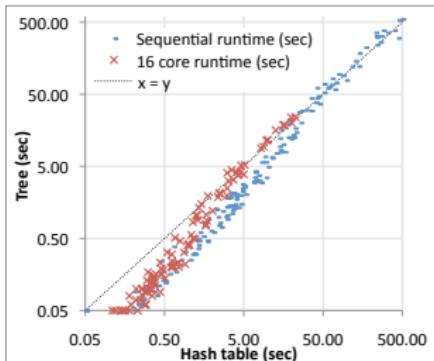


Information theoretical lower bound?

- ▶ View states as stream of variables: $\langle v_1^1, \dots, v_K^1 \rangle, \langle v_1^2, \dots, v_K^2 \rangle, \dots$ with $|v_j^i| = 2^{32}$
- ▶ $p(v_j^i = v_j^{i-1}) = \frac{K-1}{K}$ and $p(v_j^i \neq v_j^{i-1}) = \frac{1}{K}$ (under-estimation)
- ▶ Entropy per state: $K \times H(s_j^i) \approx \log_2(2^{32}) + \log_2(K)$ bits $\approx 1 + \epsilon$ integer

Experiments from 2011 [BEEM database]

LAARMAN, VAN DE POL, WEBER [SPIN11]

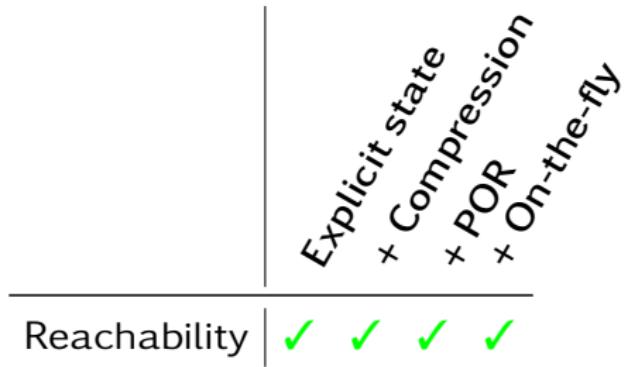


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- ▶ Halve the root table with Cleary compact hash table [MEMICS11]

Reachability

- ▶ Scalability from merging tables & incremental updates
- ▶ Correctness proved by hand
 - ▶ The recursive tree function is an injection [SPIN11]



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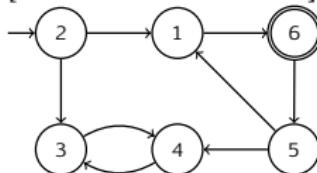
		Explicit state	Compression	POR	On-the-fly	
		Reachability	✓	✓	✓	✓
		LTL	?	?	?	?

Still only safety...

LTL

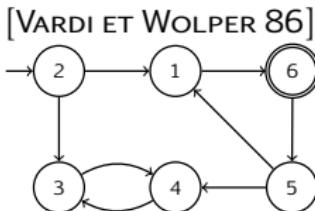
The ω -language of the Büchi automaton represents all counter examples

[VARDI ET WOLPER 86]



LTL

The ω -language of the Büchi automaton represents all counter examples



“It is as yet an open problem how a liveness verification algorithm could be generalized to the use of more than two processing cores while retaining a low search complexity.”

[HOLZMANN '07]

“One of the most important open problems of parallel LTL model checking is to design an on-the-fly scalable parallel algorithm with linear time complexity.”

[BRIM, BARNAT ET ROČKAI '11]

Nested Depth-First Search for LTL

[COURCOUBETIS'93]

```
procedure DFSblue(s)
    s.cyan := true
    for all s' in post(s) do
        if  $\neg t.\text{blue} \wedge \neg t.\text{cyan}$  then
            DFSblue(s')
        if accepting(s) then
            DFSred(s)
        s.blue := true
        s.cyan := false
procedure DFSred(s)
    s.red := true
    for all s' ∈ post(s) do
        if t.cyan then ExitCycle
        if  $\neg t.\text{red}$  then DFSred(s')
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Nested DFS (NDFS)

- ▶ Linear time

Nested Depth-First Search for LTL

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```

Nested DFS (NDFS)

- ▶ Linear time
- ▶ DFS itself is likely not parallelizable
 - ▶ DFS order is a P-complete problem
 - ▶ We assume: $P \neq NC$

Multi-core Nested Depth-First Search (Principle)

[ATVA11], [PDMC11], [ATVA12]

code for worker p :

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$s.\text{cyan}[p] := \text{true}$

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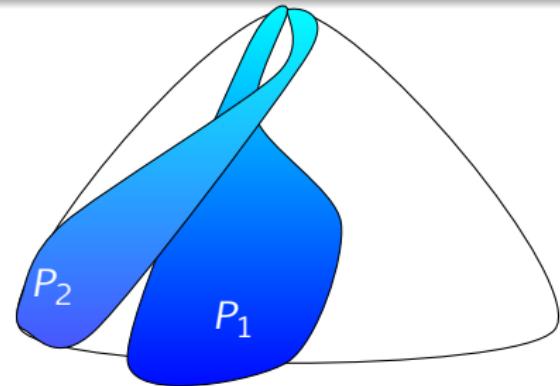
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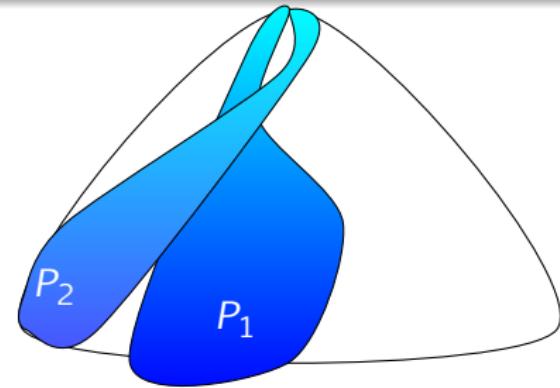
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- ▶ In reality more **synchronization!**
- ▶ LAARMAN, WIJS ET AL. [ATVA11]
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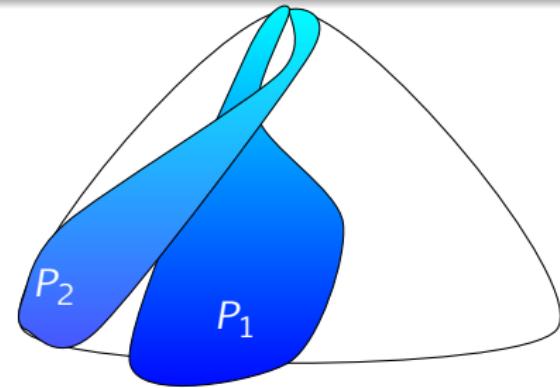
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- ▶ LAARMAN, WIJS ET AL. [ATVA11]
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EVANGELISTA, LAARMAN ET AL. [ATVA12]
- ▶ **Lemma 4:** Blue states have blue or cyan successors:

$$\text{Blue} \subseteq \bigcup_p \square (\text{Blue} \cup \text{Cyan}_p).$$

LTL and Partial-Order Reduction

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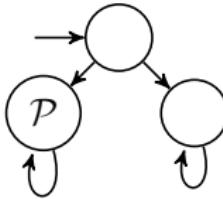
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LTL and Partial-Order Reduction

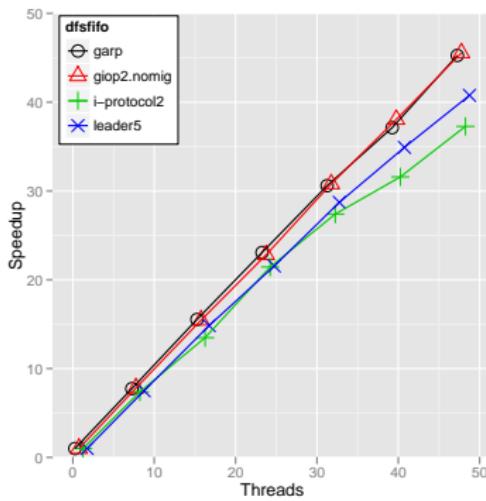
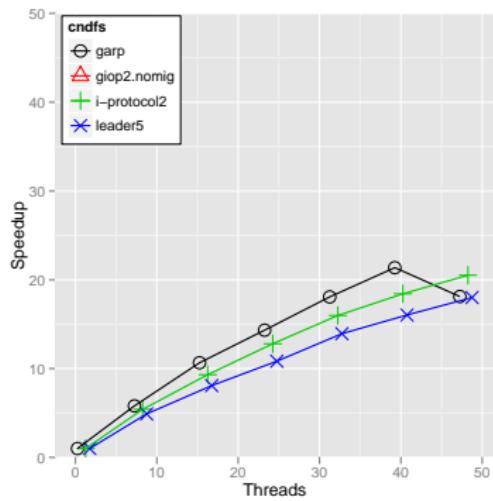
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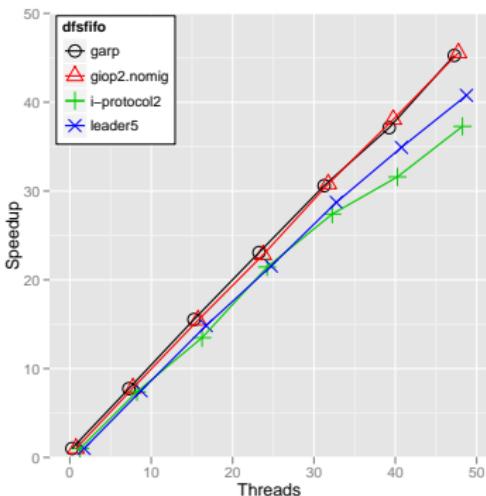
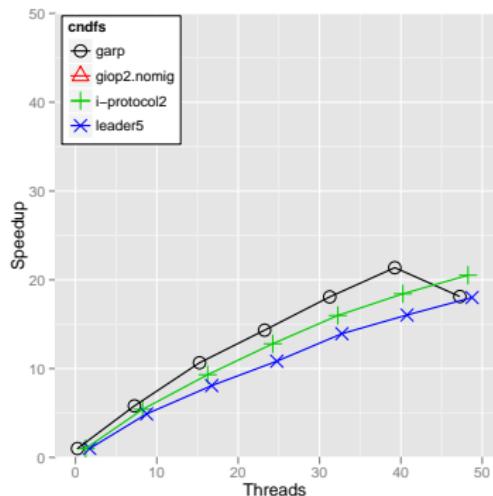
- ▶ For **livelocks** (\supset LTL), any unfair cycle is a counter example!
- ▶ Parallel DFS_{FIFO} LAARMAN ET FARAGÓ [NFM13]



Experiments: LTL with Partial-Order Reduction



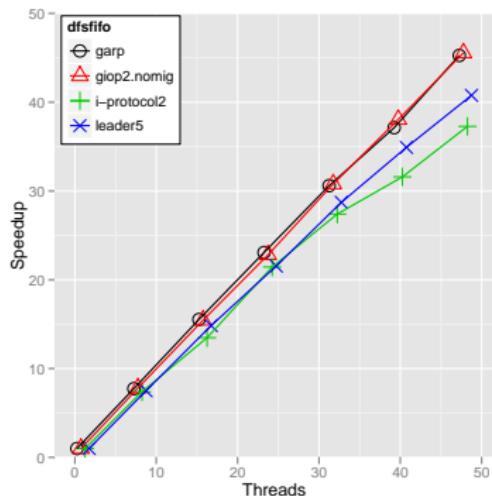
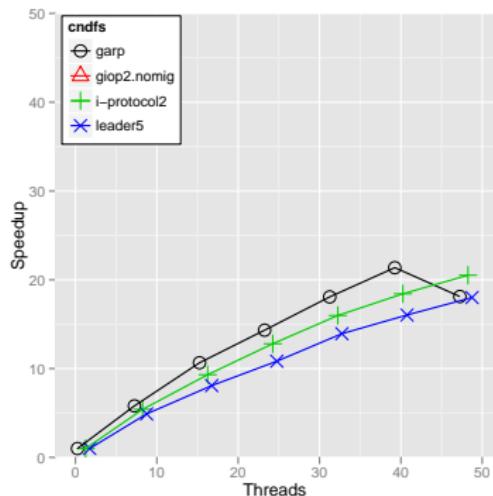
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Partial-order reductions:

	LTSMIN DFS _{FIFO}	SPIN NDFS
leader	0.49%	1.15%
garp	2.18%	12.73%
giop	1.86%	2.42%
i-prot	31.83%	41.37%

Experiments: LTL with Partial-Order Reduction



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	DFS _{FIFO}	NDFS
leader	0.49%	1.15%
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Max. model size explored in 30 min.

cores	LTSMIN	DiViNE
	DFS _{FIFO}	OWCTY
1	12	9
48	15	11

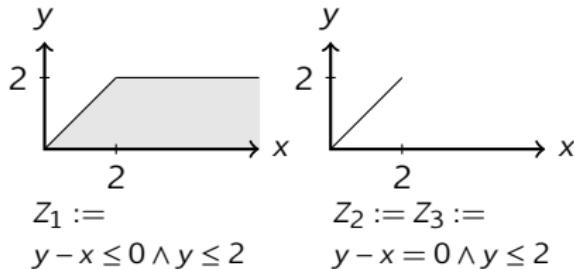
DFS_{FIFO} VS OWCTY + POR [BRIM ET AL '10]

Formalism	Property	Explicit state + Compression	+ POR	+ On-the-fly
Plain	Reachability	✓	✓	✓
	LTL	✓	✓	✗
 Livelocks	✓	✓	✓

Formalism		Property	Explicit state + Compression + POR + On-the-fly			
			✓	✓	✓	✓
Plain	Reachability	✓	✓	✓	✓	✓
	LTL	✓	✓	✗	✓	✓
 Livelocks	✓	✓	✓	✓	✓
Timed	Reachability	?	?	?	?	?
	LTL	?	?	?	?	?

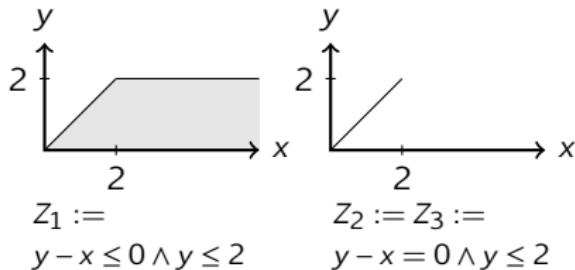
Timed Automata

States are semi-symbolic: $s = \langle d, \sigma \rangle$ (finite continuous-time abstraction)



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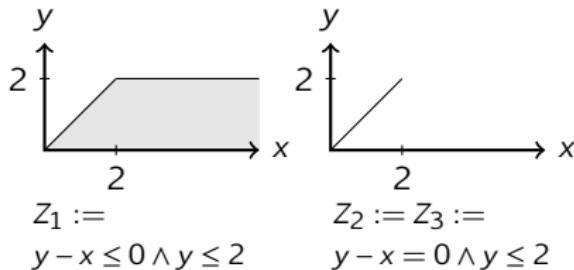
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Subsumption is a simulation relation which allows another, dynamic abstraction

Timed Automata

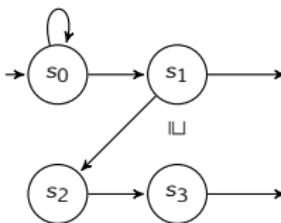
DALSGAARD, LAARMAN, OLESEN, LARSEN, VAN DE POL [FORMATS12]

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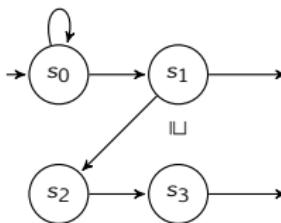
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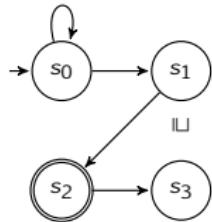
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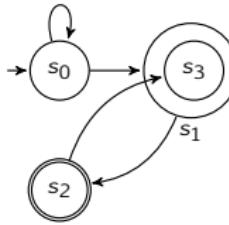
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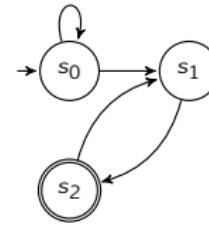
- ✗ Subsumption does not preserve Büchi emptiness! [TRIPAKIS'09]



Timed abstraction



$s_3 \sqsubseteq s_1$



subsumption

Analysis of accepting cycles/spirals with subsumption

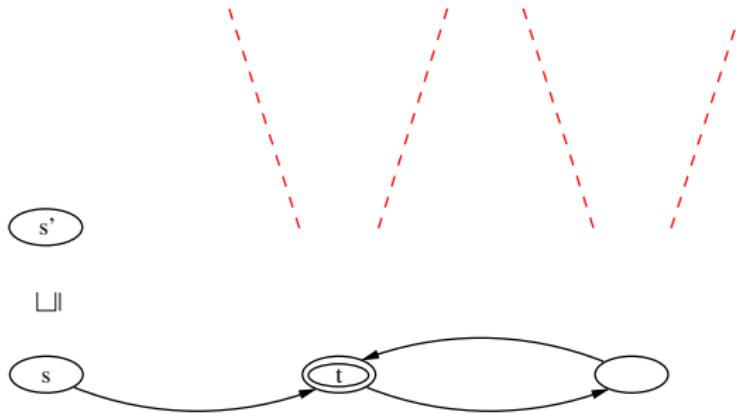
LAARMAN, OLESEN, DALSGAARD, LARSEN, VAN DE POL [CAV13]

Lemma: If s has an accepting cycle then any $s' \sqsupseteq s$ has it as well

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Preservation of accepting cycles

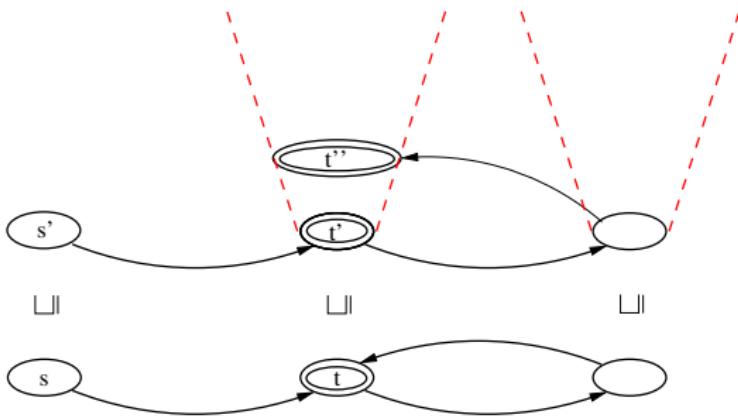
Proof Sketch

$$\begin{array}{c}
 s' \\
 \sqsupseteq \\
 s \quad \xrightarrow{*} \quad t \quad \xrightarrow{+} \quad t
 \end{array}$$

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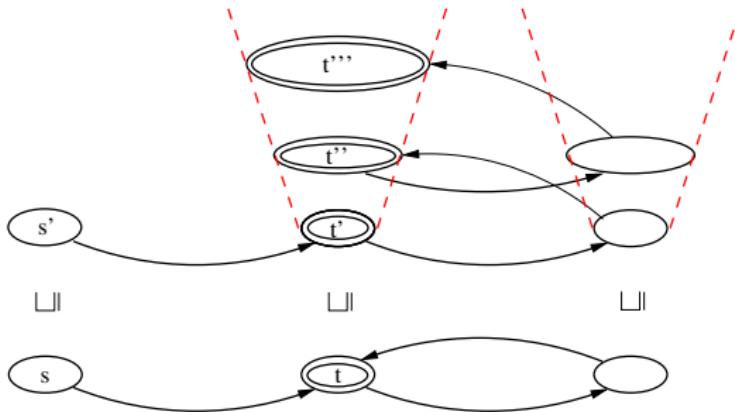
Proof Sketch

$$\begin{array}{ccccccc}
 s' & \xrightarrow{*} & t' & \xrightarrow{+} & t'' \\
 \sqcup & & \sqcup & & \sqcup \\
 s & \xrightarrow{*} & t & \xrightarrow{+} & t
 \end{array}$$

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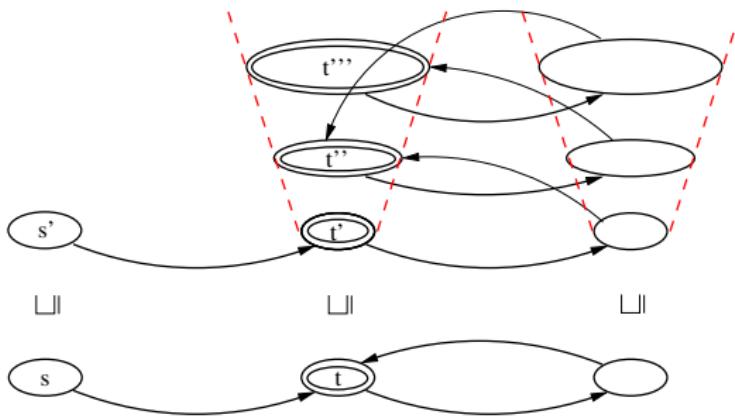
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$$\begin{array}{ccccccccc}
 s' & \xrightarrow{*} & t' & \xrightarrow{+} & t'' & \xrightarrow{+} & \dots & \xrightarrow{+} & t''' \\
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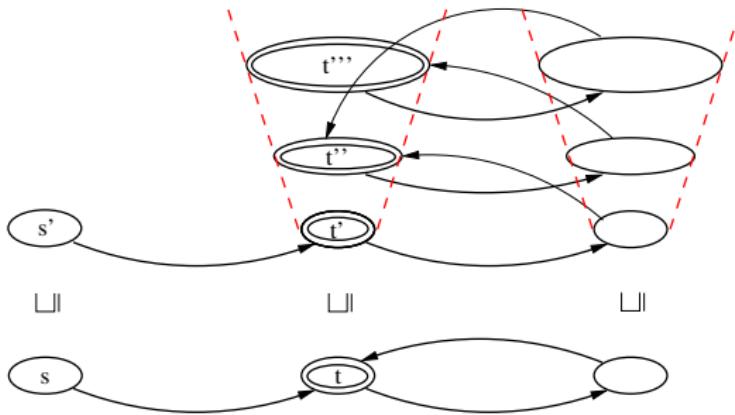
Proof Sketch

s'	\rightarrow^*	t'	\rightarrow^+	t''	\rightarrow^+	\dots	\rightarrow^+	t''''	\rightarrow^+	\dots
$\sqcup\!\sqcup$		$\sqcup\!\sqcup$		$\sqcup\!\sqcup$				$\sqcup\!\sqcup$		$\sqcup\!\sqcup$
s	\rightarrow^*	t	\rightarrow^+	t	\rightarrow^+	\dots	\rightarrow^+	t	\rightarrow^+	t

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Preservation of accepting cycles

Proof Sketch

s'	\rightarrow^*	t'	\rightarrow^+	t''	\rightarrow^+	\dots	\rightarrow^+	t'''	\rightarrow^+	$\textcolor{red}{x}$
$\sqcup\sqcup$		$\sqcup\sqcup$		$\sqcup\sqcup$				$\sqcup\sqcup$		$\sqcup\sqcup$
s	\rightarrow^*	t	\rightarrow^+	t	\rightarrow^+	\dots	\rightarrow^+	t	\rightarrow^+	t

Lemma: If t' has an accepting spiral then t' has an accepting cycle

Results with Parallel Timed Reachability / LTL

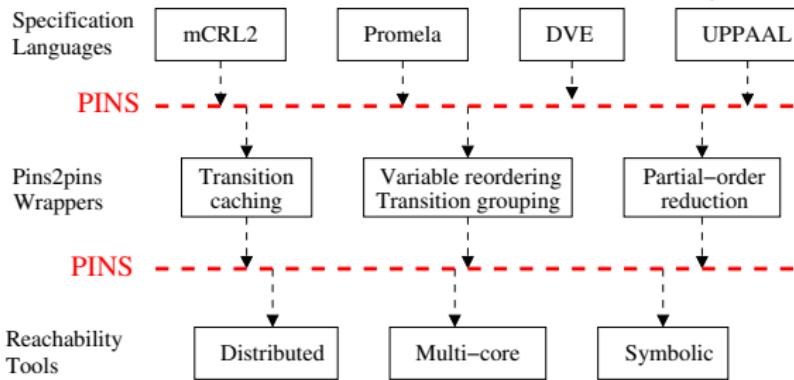
LAARMAN, OLESEN, DALSGAARD, LARSEN, VAN DE POL [CAV13][FORMATS2012]

- ▶ Add full LTL to timed automata
- ▶ Runtimes 60x faster than UPPAAL on 48 cores
- ▶ Up to 70x reductions due to subsumption
- ▶ Tree compression for large discrete states

LTSmin

LTSMIN BLOM, VAN DE POL, WEBER [CAV09]

<http://fmt.cs.utwente.nl/tools/ltsmin/> (open source)



Other work

- ▶ Guard-based POR PATER, LAARMAN, VAN DE POL [SPIN13]
- ▶ PROMELA formalism VAN DER BERG ET LAARMAN [PDMC12]
- ▶ LTSmin tool LAARMAN, WEBER, VAN DE POL [NFM11]

Contributions

Formalism	Property	publications			
		Explicit state x Compression x POR x On-the-fly			
Plain	Reachability	✓ ✓ ✓ ✓			[FMCAD10][SPIN11][MEMICS11]
	LTL	✓ ✓ 1/2 ✓			[ATVA11][PDMC11][ATVA12]
 Livelocks	✓ ✓ ✓ ✓			[SPIN13][NFM13]
Timed	Reachability	✓ ✓ – ✓			[FORMATS12]
	LTL	✓ ✓ – ✓			[CAV13]

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 Livelocks	✓	✓	✓	✓	?
Timed	Reachability	✓	✓	—	✓	?
	LTL	✓	✓	—	✓	?

Other work

- ▶ Multi-core BDDs VAN DIJK, LAARMAN, VAN DE POL [PDMC12]

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Timed	Reachability	✓	✓	—	✓	?
	LTL	✓	✓	—	✓	?

Other work

- ▶ Multi-core BDDs VAN DIJK, LAARMAN, VAN DE POL [PDMC12]
- ▶ One-Way-Catch-Them Young (LTL) [BARNAT,BRIM,ROČKAI'01]
- ▶ Topological sort proviso (POR) [BARNAT,BRIM,ROČKAI'10]
- ▶ CTL [SAAD ET AL'12]

Future work

Formalism	Property	Explicit state + Compression + pOR + On-the-fly			
Plain	Reachability	✓	✓	✓	✓
	LTL	✓	✓	1/2	✓
Timed	Reachability	✓	✓	-	✓
	LTL	✓	✓	-	✓

Future work

Formalism	Property	Explicit state + Compression + PQR + On-the-fly		
Plain	Reachability	✓	✓	✓
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	CTL	?	?	?
Timed	Reachability	✓	✓	-
	LTL	✓	✓	-
	CTL	?	?	?

Future work

Formalism		Property	Techniques				
			Explicit state + Compression	+ POR	+ On-the-fly	Symbolic	Distributed
Plain	Reachability		✓	✓	✓	✓	✓ ?
	LTL		✓	✓	1/2	✓	? ?
	CTL		?	?	?	?	?
Timed	Reachability		✓	✓	-	✓	? ?
	LTL		✓	✓	-	✓	? ?
	CTL		?	?	?	?	?

Future work

Formalism		Property	Techniques			
			Explicit state + Compression	+ POR	+ On-the-fly	Symbolic Distributed
Plain	Reachability		✓	✓	✓	✓
	LTL		✓	✓	1/2	✓
	CTL		?	?	?	?
Timed	Reachability		✓	✓	—	✓
	LTL		✓	✓	—	✓
	CTL		?	?	?	?
Stoch.	Reachability		?	?	?	?
	LTL		?	?	?	?
	CTL		?	?	?	?

Future work

Formalism	Property	Explicit state + Compression	+ POR	+ On-the-fly	Symbolic	Distributed
Plain	Reachability	✓	✓	✓	✓	?
	LTL	✓	✓	✓	✓	?

Other questions

- ▶ Can our parallel DFS-based solutions be generalized?
 - ▶ (Bottom-)SCC detection
 - ▶ Emptiness of {Tree, Rabin, Streett} automata, etc.
 - ▶ What search-order property is preserved?

Stoch.	Reachability	?	?	?	?	?
	LTL	?	?	?	?	?
	CTL	?	?	?	?	?

Multi-core Nested Depth-First Search (Principle) [ATVA11][FDMC11][ATVA12]

```

code for worker  $p$ :
procedure DFSblue( $s, p$ )
  s.cyan[ $p$ ] := true
  for all  $s' \in \text{shuffle}(\text{post}(s))$  do
    if  $\neg s'.\text{blue} \wedge \neg t.\text{cyan}[p]$  then
      DFSblue( $s', p$ )
  if accepting( $s$ ) then
    DFSred( $s, p$ )
  s.blue := true
  s.cyan[ $p$ ] := false
procedure DFSred( $s, p$ )
  s.red[ $p$ ] := true
  for all  $s' \in \text{post}(s)$  do
    if  $t.\text{cyan}[p]$  then ExitCycle
    if  $\neg t.\text{red}[p]$  then DFSred( $s', p$ )

```

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Static partitioning or shared hash table [FMCAD10]

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Multi-core NDFS

- States in shared tree/table
- Independent forward search
- Share blue color
- repair DFS order (not shown)

Static partitioning

- On-the-fly (BFS)
- Scalability (communication on queues)

Shared hash table

- On-the-fly: (pseudo) DFS & BFS
- ? Scalability

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Recursive indexing [HOLZMANN 97][BLOM ET AL. 08]

H_K

$(K-1) \times H_2$

- Combinatorial \rightarrow balanced tree $(N + 2\sqrt{N} + 4\sqrt[N]{N}) \cdots \approx N)$
- Compresses states of length K to almost 2^k
- Hard to parallelize (flattener)

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Experiments from 2011 [BEEM database] [SPIN11]

Delta optimal

Benchmark Category	Percentage
Delta optimal	41.0%
Sequential	11.0%
LTL	11.0%
ATVA11	11.0%
SPIN13	11.0%
NFM13	11.0%

Information theoretical optimum?

- View states as K -periodic stream of 2^{32} -valued variables
- Information entropy per state: $\log_2(2^{32}) + \log_2(K)$ bits $\approx 1 + \epsilon$ integer
- Halfie root table with compact hash table [WMCSCS11]

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Contributions

Formalism	Property	Explicit state compression	On-the-fly	Symbolic	publications
Plain	Reachability	✓ ✓ 1/2 ✓ ✓	✓ ✓ 1/2 ✓ ?	✓ ✓ ✓ ✓ ?	[FMCAD10][SPIN11][MEMICS11] [ATVA11][FDMC11][ATVA12] [SPIN13][NFM13]
Timed	Reachability	✓ ✓ = ✓ ?	✓ ✓ = ✓ ?	✓ ✓ = ✓ ?	[FORMATS12] [CAV13]
LTL					

Related work

- Multi-core BDDs [FMCAD13][1]
- One-Way-Catch-Them Young (LTL) [BANAKI,BERK,RÖCKA'01]
- Topological sort prepos (POR) [BANAKI,BERK,RÖCKA'10]
- CTL [SAAD ET AL 2012]

UNIVERSITY OF TWENTE Multi-Core Model Checking November 5, 2013 24 / 26